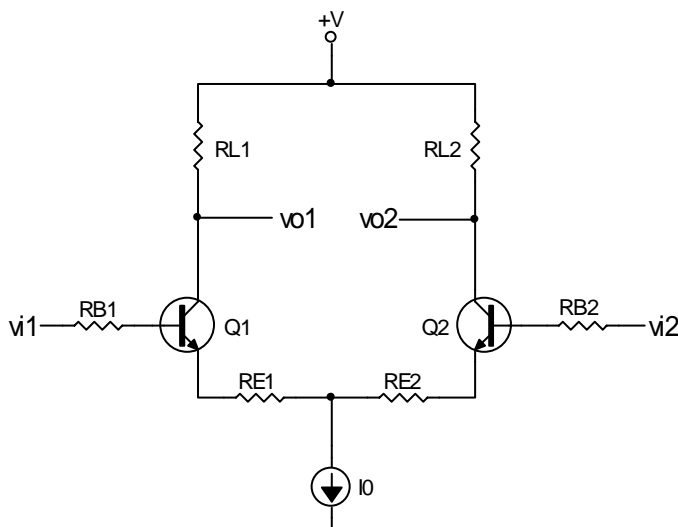


## Temperature Compensation Of BJT Differential Amplifiers

by Dennis L Feucht

The bipolar junction transistor (BJT) emitter-coupled differential-pair circuit is a familiar amplifier stage in the repertoire of analog designers, but has a surprising obscurity that needs to be revealed. This TechNote examines the emitter-circuit current source,  $I_0$ , of BJT diff-amps and the effects on amplifier gain of different implementations for it.

The widespread belief that a BJT current source can temperature-compensate the diff-amp is true, but the conditions for it do not appear to be widely known, based on most designs. The typical circuit is shown below.



This is a differential-input, differential-output voltage amplifier. Both input and output quantities are differential, and the incremental gain of the circuit is:

$$A_v = \frac{v_o}{v_i} = \frac{v_{o2} - v_{o1}}{v_{i2} - v_{i1}} = \frac{A_{v2} \cdot v_{i2} - A_{v1} \cdot v_{i1}}{v_{i2} - v_{i1}} = \frac{v_{o2}}{v_{i2}} \Big|_{v_{i1}=0} - \frac{v_{o1}}{v_{i1}} \Big|_{v_{i2}=0} =$$

$$= -\alpha_2 \cdot \frac{R_{L2}}{r_{e1} + r_{e2} + R_{E1} + R_{E2} + R_{B1}/(\beta_1 + 1) + R_{B2}/(\beta_2 + 1)}$$

$$- \left( -\alpha_1 \cdot \frac{R_{L1}}{r_{e1} + r_{e2} + R_{E1} + R_{E2} + R_{B1}/(\beta_1 + 1) + R_{B2}/(\beta_2 + 1)} \right)$$

The condition for differential amplification is that  $A_{v1} = A_{v2}$ . The circuit is made symmetrical for:

$$R_E = R_{E1} = R_{E2} ; R_B = R_{B1} = R_{B2} ; R_L = R_{L1} = R_{L2} ; \beta = \beta_1 = \beta_2, Q_1, Q_2 \text{ matched}$$

Then the gain simply becomes:

$$A_v = 2 \cdot A_{v1} = 2 \cdot A_{v2} = -\alpha \cdot \frac{R_L}{r_e + R_E + R_B / (\beta + 1)} = -\alpha \cdot \frac{R_L}{r_M}$$

A goal of good design is to make  $A_v$  a fixed value. The choice of resistors with a low temperature coefficient (TC) and sufficiently tight accuracy is one factor. This is usually easy to achieve, though for high-precision design, the change in resistance due to change in ambient temperature is a factor to be considered. Even

more so are *thermals*, changes in resistance due to changes in power dissipation with  $v_i$ . For very precise designs, the change in resistance with applied voltage must be considered too.

Other transistor parameters than the two ( $r_e$  and  $\beta$ ) of the BJT T model used here - namely,  $r_o$  - also need to be included for precision design. We will assume that the BJTs have a sufficiently high Early voltage that  $r_o$  need not come into our list of considerations -- at least not here. In practice, this assumption is often valid.

BJTs are typically the least ideal elements of the circuit. From the gain formula, it is evident that two BJT parameters affect gain, the incremental emitter resistance,  $r_e$ , and  $\beta$ . For high  $\beta$  -- that is, for  $\beta \gg 1$  -- the gain factor,

$$\alpha = \frac{\beta}{\beta + 1}$$

approaches 1. For a typical  $\beta$  value of 200, then  $\alpha = 0.995$ , contributing a gain error of 0.5%. If that is too much error,  $\alpha$ -compensation techniques are required. Usually, this error can be compensated by including it in the gain formula, as we have done. What is more important is how much it drifts with temperature. Typical  $TC(\beta) \cong 1\%/^{\circ}C$ , then for large  $\beta$ ,  $\alpha$  has nearly a zero TC of around 50 ppm;  $\alpha$  is not much of a problem.

The transresistance expression of  $A_v$  -- the denominator -- is the resistance across which the input voltage develops the common (emitter) current. The output current is modified by  $\alpha$ , which accounts for loss along the way from the emitter circuit. This transresistance,  $r_M$ , also includes  $\beta$  in the  $R_B$  term. If  $R_B$  is kept small, and the inputs are driven by voltage sources, then this  $\beta$  is of no concern. If the sources are high in resistance, then the  $R_B$  term will affect gain by  $\beta$  variation with temperature. Its  $1\%/^{\circ}C$  variation is scaled down by the extent to which  $R_B/(\beta + 1)$  is not dominant in  $r_M$ . Thus, keeping this term negligible is another design factor.

The most troublesome term in  $r_M$  is  $r_e$ , for it varies with temperature and emitter current,  $I_E$ , according to:

$$r_e = \frac{V_T}{|I_E|} = \frac{kT/q_e}{|I_E|} \cong \frac{26 \text{ mV}}{|I_E|}, T = 300 \text{ K}$$

Thus  $r_e$  varies with the thermal voltage,  $V_T$ , which varies in proportion with absolute temperature:

$$\frac{dV_T}{dT} = \frac{V_T}{T}$$

At 300°K (about 80°F), this is  $1/300^{\circ}K$  or about  $0.33\%/^{\circ}K = 0.33\%/^{\circ}C$ . For laboratory-quality instrument design, let us suppose the temperature range over which the equipment ought to be able to operate within its specifications is 15°C from room temperature, about  $25^{\circ}C \pm 15^{\circ}C$ , or 10°C to 40°C. Over a 15°C change from ambient,  $V_T$  changes about 5% -- far too much for most precision designs. Therefore,  $V_T$  variation in gain needs to be compensated.

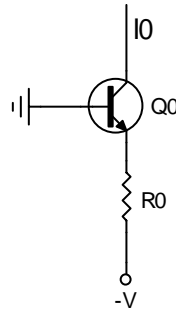
The simplest compensation for  $r_e$  is to make it a negligible term (along with the  $R_B$  term) in  $r_M$ . This is accomplished by making  $R_E$  dominant. For  $R_E \gg r_e$ , the drift in  $r_e$  affects gain far less than 5%. In many cases, dominant external emitter resistance solves the drift problem, but at the expense of gain and power dissipation. By increasing  $I_0$ , then  $r_e$  is reduced proportionally, though circuit power increases. This is undesirable for power-limited equipment and it also exacerbates thermals by increasing  $\Delta P_D(v_i)$  in the BJTs.

In some cases,  $r_e$  cannot be made negligible, and some compensation for it is desired. One of the most common schemes is to make  $I_0$  track  $r_e$  and cancel its effect, at least approximately. To make  $I_0$  have the TC of  $V_T$ , the simplest approach is to use a BJT current source implementation of  $I_0$ . The  $b$ - $e$  junction voltage of the current-source BJT then decreases with temperature,  $I_0$  increases, and decreases  $r_e$ .

## Current-Source Circuits

The first circuit sourcing  $I_0$  that we will consider is simply a resistor,  $R_0$ , returned to a negative supply. This *long-tailed* current source approaches an ideal current source as the supply voltage,  $-V$ , approaches negative infinity, along with the value of  $R_0$ . It does nothing to compensate for the TC of  $r_e$ .

The second implementation to consider is shown below.



This simple circuit has a voltage across  $R_0$  of  $V - V_{BE}(Q_0)$ . As temperature,  $T$ , increases,  $V_{BE}$  decreases, but not with the TC of  $V_T$ . The other major BJT parameter affecting  $V_{BE}$  is the saturation current,  $I_S$ , as found in the  $p$ - $n$  junction ( $b$ - $e$  junction) voltage equation:

$$V_{BE} = V_T \cdot \ln\left(\frac{I_C}{I_S(T)}\right), I_C \gg I_S$$

For a typical BJT, such as a PN3904,  $I_S \approx 10^{-14}$  A. Then 1 mA of current produces a  $V_{BE} \approx 0.65$  V.

Both  $V_T$  and  $I_S$  contribute to the  $TC(V_{BE})$ .  $I_S$  has a greater effect than  $V_T$  and of opposite polarity on  $V_{BE}$ , resulting in a combined effect of about  $-2$  mV/ $^{\circ}$ C for  $V_{BE}$ . (For more on BJT TC effects, see the volume, *Signal-Processing Circuits of Analog Circuit Design*, available at <http://www.innovatia.com>.) It is therefore more important to cancel  $I_S$  effects than those of  $V_T$ . Depending on the relative values of  $V$  and  $V_{BE}$ , the effect of the  $TC(V_{BE})$  can be scaled by choice of  $R_E$  and supply voltage,  $V$ , which is often constrained by system-level design. By adding a resistor network between the emitter and ground, a Thévenin equivalent supply voltage and value of  $R_0$  can be independently set. If scaled properly, as  $T$  increases,  $V_{BE}$  decreases and  $I_0$  increases. If the increase is made to be such that the reduction in  $r_e$  due to it cancels the increase in  $r_e$  due to  $V_T$ , then  $r_e$  and gain remain constant.

The  $TC(r_e)$  is calculated as follows, by differentiating  $r_e$  with respect to  $T$ :

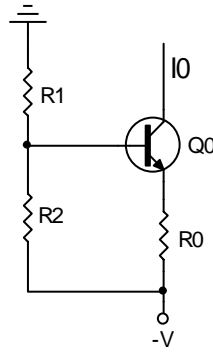
$$\frac{dr_e}{dT} = \frac{d}{dT}\left(\frac{V_T}{I_E}\right) = \left(\frac{1}{I_E}\right) \cdot \frac{dV_T}{dT} - \frac{V_T}{I_E^2} \cdot \frac{dI_E}{dT} = \frac{V_T}{I_E} \cdot \left(\frac{1}{V_T} \cdot \frac{dV_T}{dT}\right) - \frac{V_T}{I_E} \cdot \left(\frac{1}{I_E} \cdot \frac{dI_E}{dT}\right) = r_e \cdot [TC\%(V_T) - TC\%(I_E)]$$

where,  $TC\%$  is the fractional change in TC.

The  $TC\%(I_0) = TC\%(I_E)$  can be determined as follows. The only change across  $R_0$  is due to  $V_{BE}$ . Therefore, the fractional change in  $I_0$  with  $T$  is:

$$TC\%(I_0) = \frac{dI_0/dT}{I_0} = \frac{-(dV_{BE}/dT)/R_0}{I_0} = \frac{-dV_{BE}/dT}{V - V_{BE}} = \frac{+2 \text{ mV}/^{\circ}\text{C}}{V - V_{BE}}$$

For  $TC\%(I_0) = TC\%(V_T) = 1/T \cong 0.33\%/^{\circ}\text{C}$ , and the voltage across  $R_0$ ,  $V - V_{BE} = 0.6\text{ V}$ . With  $-V = -1.25\text{ V}$ , this is not an attractive compensation scheme. The polarity of  $TC(I_0)$  is correct for compensation, but not its magnitude, which leads to the next scheme, shown below.



This implementation of  $I_0$  is more versatile and more common in occurrence than the previous scheme. The base divider provides extra freedom for setting  $TC\%(I_0)$  which, for ignored  $TC(\beta)$ , is now:

$$\begin{aligned}
 TC\%(I_0) &= \frac{1}{I_0} \cdot \frac{dI_0}{dT} = \frac{1}{I_0} \cdot \frac{d}{dT} \left( \frac{\left( \frac{R_2}{R_1 + R_2} \right) \cdot V - V_{BE}}{R_0 + (R_1 \parallel R_2) / (\beta + 1)} \right) = \frac{1}{I_0} \cdot \frac{\left( -\frac{dV_{BE}}{dT} \right)}{R_0 + (R_1 \parallel R_2) / (\beta + 1)} \\
 &= \frac{\left( -\frac{dV_{BE}}{dT} \right)}{\left( \frac{R_2}{R_1 + R_2} \right) \cdot V - V_{BE}} = \frac{\frac{1}{V_{BE}} \cdot \left( -\frac{dV_{BE}}{dT} \right)}{\left( \frac{R_2}{R_1 + R_2} \right) \cdot \frac{V}{V_{BE}} - 1} = \frac{-TC\%(V_{BE})}{\left( \frac{R_2}{R_1 + R_2} \right) \cdot \frac{V}{V_{BE}} - 1}
 \end{aligned}$$

The divider ratio that gives the correct compensation can now be found. When  $TC\%(I_0)$  is set equal to  $TC\%(V_T)$ , then:

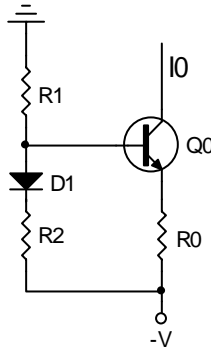
$$\left( \frac{R_2}{R_1 + R_2} \right) \cdot \frac{V}{V_{BE}} = \frac{-TC\%(V_{BE})}{TC\%(V_T)} + 1 = \frac{+2\text{ mV}/^{\circ}\text{C}/V_{BE}}{0.33\%/^{\circ}\text{C}} + 1 = \frac{0.6\text{ V} + V_{BE}}{V_{BE}}$$

or,

$$\frac{R_2}{R_1 + R_2} = \frac{0.6\text{ V} + V_{BE}}{V} \cong \frac{1.25\text{ V}}{V}$$

for  $V_{BE} = 0.65\text{ V}$ . This result is interesting; whatever the value of  $V$ , the unloaded divider voltage must be  $1.25\text{ V}$  for gain compensation. This is also the voltage of bandgap references, as well it should be. Bandgap circuits use the negative  $TC(V_{BE})$  and scale it to cancel the positive  $TC(V_T)$ . When this is done the resulting bandgap voltage always comes out to be close to  $1.25\text{ V}$ , and varies slightly with BJT doping levels.

Another current-source variation that is often used to provide rough temperature compensation is to insert a diode in series with  $R_2$ , as shown below.



The usual explanation is that the TC of the diode compensates for the TC of the BJT  $b-e$  junction, resulting in a more stable  $I_0$ . A typical example is to use a 1N4152 diode to compensate a PN3904. The diode and BJT  $b-e$  junctions are quite different, however. The diode doping levels are far less than even the BJT base, in order to achieve a higher breakdown voltage. The emitter minority carrier concentration is made intentionally large for good emitter injection efficiency into the base, at the expense of  $V_{BE}$  reverse breakdown, which is typically around 7 V, much below the 60 V of the diode. The point is that although both junctions are silicon, they are rather unmatched.

Suppose, however, that a similar BJT is used as a diode, with base connected to collector. Then the junction matching is better (though not as good as adjacent integrated BJTs), and allowing for  $\alpha \cong 1$ , then applying KVL around the BJT input loop:

$$V_T \cdot \ln\left(\frac{I_0}{I_D}\right) = I_D \cdot R_2 - I_0 \cdot R_0, \text{ or, } I_0 = \frac{I_D \cdot R_2 - V_T \cdot \ln(I_0 / I_D)}{R_0}$$

where,  $I_D$  is the diode current. If the junction currents are equal, the TC due to  $V_T$  is removed and the  $\text{TC}\%(I_0) \cong 0\%/^{\circ}\text{C}$ . This is useful for applications where a stable current source is needed, but it does not compensate  $r_e$  of the diff-amp. The currents must deliberately be set unequal to achieve the desired TC, and for a compensating polarity of TC, it must be positive. Consequently, we must have  $I_D > I_0$ .

The  $\text{TC}\%(I_0)$  is found through implicit differentiation of  $I_0$  in the above equation:

$$\begin{aligned} \text{TC}\%(I_0) &= \frac{1}{I_0} \cdot \frac{dI_0}{dT} = \frac{1}{I_0 \cdot R_0} \cdot \left( -V_T \cdot \frac{d}{dT} \ln\left(\frac{I_0}{I_D}\right) - \ln\left(\frac{I_0}{I_D}\right) \cdot \frac{dV_T}{dT} \right) \\ &= -\frac{V_T}{I_0 \cdot R_0} \cdot \left( \text{TC}\%(I_0) + \frac{1}{T} \cdot \ln\left(\frac{I_0}{I_D}\right) \right) \end{aligned}$$

With additional algebraic manipulation:

$$\text{TC}\%(I_0) = -\frac{(V_T / I_0 \cdot R_0) \cdot \ln(I_0 / I_D)}{T \cdot (1 + V_T / I_0 \cdot R_0)}$$

Then to compensate, set  $\text{TC}\%(I_0) = \text{TC}\%(V_T) = 1/T$  and solve:

$$\frac{I_D}{I_0} = \exp\left(1 + \frac{I_0 \cdot R_0}{V_T}\right)$$

Because of the exponential function, practical current ratios require that the voltage across  $R_0$  be not much larger than  $V_T$ . For  $I_0 = 2$  mA,  $R_0 = 22$   $\Omega$ , and  $V_T = 26$  mV, then the voltage across  $R_0$  is 44 mV, or  $1.69 \cdot V_T$ , and  $I_D = 14.77 \cdot I_0 = 29.5$  mA, larger than is desired in most designs. Such small values of  $R_0$  are required to keep  $R_0$  from dominating the emitter circuit so that the TC of  $V_{BE}$  can be expressed. Yet in many designs,  $R_0$  is relatively large and its voltage drop far exceeds  $V_T$ . As a consequence, the TC%( $V_T$ ) of  $r_e$  is not correctly compensated and a TC drift in gain exists.

The previous scheme, which omitted the base diode, was only slightly better in allowing for larger  $R_0$  voltage. Perhaps we should go in the opposite direction and add a diode or two in the emitter. The TC of the combined junctions would be multiplied by the number of them, and that would allow  $R_E$  to be made proportionally larger. It is usually not desirable to add a large number of series diodes because the static (dc) stability of  $I_0$  is not benefited. Consequently, use of the diff-amp current source to temperature-compensate  $r_e$  results in a circuit requiring careful static design.  $I_0$  is then made sensitive to junction parameters, and these parameters, such as  $I_S$ , have a somewhat wide tolerance among discrete transistors, even of the same part number. Expect as much as 50 mV of variation among PN3904 BJTs at the same current and temperature. This compensation method is best suited for monolithic integration.

## Closure

The widespread belief that a BJT current source can temperature-compensate a BJT diff-amp is true, but it often does not. Temperature compensation of  $I_0$  for a constant  $r_e$  results in low voltage across the current-source external emitter resistance,  $R_0$  -- so low that it can make accurate setting of  $I_0$  infeasible.

Consequently, except for more elaborate schemes which amplify  $V_T$ , the dominant- $R_E$  approach to diff-amp gain stability appears to still be the best.

## Acknowledgement

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